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AUTHOR(S):

Suzuki, Kanako

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Unbounded solutions to some reaction-diffusion-ODE systems modeling pattern formation

Kanako Suzuki

College of Science, Ibaraki University,
2-1-1 Bunkyo, Mito 310-8512, Japan
kanako.suzuki.sci2@vc.ibaraki.ac.jp

1 Introduction

The mechanism of pattern formation is one of the most interesting subjects in mathematical biology. A. M. Turing proposed a notion of the *diffusion-driven instability* in the seminal paper [13]. It means that a reaction between two chemicals with different diffusion rates may cause a destabilization of a spatially homogeneous state, thus leading to the formation of nontrivial spatial structure. This is a bifurcation that arises in a reaction-diffusion system, when there exists a spatially homogeneous stationary solution which is asymptotically stable with respect to spatially homogeneous perturbations but unstable to spatially heterogeneous perturbations. Models with the diffusion-driven instability describe a process of a destabilization of stationary spatially homogeneous steady states and evolution of the system towards spatially heterogeneous steady states.

Recently, the diffusion-driven instability has been observed in models describing a coupling of cell-localized processes with a cell-to-cell communication via diffusion. Such models are of a form of systems consisting of a single ordinary differential equation coupled with a reaction-diffusion equation:

$$u_t = f(u, v), \quad v_t = D\Delta v + g(u, v), \quad (1.1)$$

such as in Refs. [4, 8, 10, 12]. We call the system in the form of (1.1) *reaction-diffusion-ODE system*. Simulations of different models of this type indicate a formation of dynamical, multimodal, and apparently irregular and unbounded structures, the shape of which depends strongly on initial conditions [1, 9, 10, 12].

A scalar reaction-diffusion equation (in a bounded, convex domain and the Neumann boundary conditions) cannot exhibit stable spatially heterogeneous patterns. Coupling it to an ODE fulfilling the following *autocatalysis* condition at the equilibrium (\bar{u}, \bar{v})

$$f_u(\bar{u}, \bar{v}) > 0 \quad (1.2)$$

leads to the diffusion-driven instability. However, in such a case, all regular Turing patterns are unstable, because the same mechanism which destabilizes constant

solutions, destabilizes also all continuous spatially heterogeneous stationary solutions, [5, 6]. This instability result holds also for discontinuous patterns in case of a specific class of nonlinearities, see also [5, 6].

In this paper, we present two examples of (1.1) to understand the dynamics of non-constant solutions of the reaction-diffusion-ODE systems exhibiting the diffusion-driven instability. In both cases, we show that they have solutions which become unbounded (blow up) in a finite time.

This is a joint work with A. Marciniak-Czochra (University of Heidelberg), G. Karch (University of Wroclaw) and J. Zienkiewicz (University of Wroclaw).

We begin our study by stating a result on the existence and boundedness of a solution to the initial boundary value problem for (1.1).

2 Existence of solutions

We consider the following system

$$u_t = f(u, v), \quad \text{for } x \in \overline{\Omega}, \quad t > 0, \quad (2.1)$$

$$v_t = \Delta v + g(u, v) \quad \text{for } x \in \Omega, \quad t > 0 \quad (2.2)$$

in a bounded domain $\Omega \subset \mathbb{R}^n$ for $n \geq 1$, with a C^2 -boundary $\partial\Omega$, supplemented with the Neumann boundary condition

$$\partial_\nu v = 0 \quad \text{for } x \in \partial\Omega, \quad t > 0, \quad (2.3)$$

where $\partial_\nu = \frac{\partial}{\partial \nu}$ and ν denotes the unit outer normal vector to $\partial\Omega$, and with initial data

$$u(x, 0) = u_0(x), \quad v(x, 0) = v_0(x). \quad (2.4)$$

The nonlinearities $f = f(u, v)$ and $g = g(u, v)$ are arbitrary C^3 -functions. Notice that equation (2.2) may contain an arbitrary diffusion coefficient which, however, can be rescaled and assumed to be equal to one.

Theorem 2.1 (Local-in-time solution). *Assume that $u_0, v_0 \in L^\infty(\Omega)$. Then, there exists $T = T(\|u_0\|_\infty, \|v_0\|_\infty) > 0$ such that the initial-boundary value problem (2.1)–(2.4) has a unique local-in-time mild solution $u, v \in L^\infty([0, T], L^\infty(\Omega))$.*

We recall that a mild solution of problem (2.1)–(2.4) is a pair of measurable functions $u, v : [0, T] \times \overline{\Omega} \mapsto \mathbb{R}$ satisfying the following system of integral equations

$$u(x, t) = u_0(x) + \int_0^t f(u(x, s), v(x, s)) \, ds, \quad (2.5)$$

$$v(x, t) = e^{t\Delta} v_0(x) + \int_0^t e^{(t-s)\Delta} g(u(x, s), v(x, s)) \, ds, \quad (2.6)$$

where $e^{t\Delta}$ is the semigroup of linear operators generated by Laplacian with the Neumann boundary condition. Since our nonlinearities $f = f(u, v)$ and $g = g(u, v)$ are locally Lipschitz continuous, to construct a local-in-time unique solution of system (2.5)–(2.6), it suffices to apply the Banach fixed point theorem.

If u_0 and v_0 are more regular, *i.e.* if for some $\alpha \in (0, 1)$ we have $u_0 \in C^\alpha(\overline{\Omega})$, $v_0 \in C^{2+\alpha}(\overline{\Omega})$ and $\partial_\nu v_0 = 0$ on $\partial\Omega$, then the mild solution of problem (2.1)–(2.4) is smooth and satisfies $u \in C^{1,\alpha}([0, T] \times \overline{\Omega})$ and $v \in C^{1+\alpha/2, 2+\alpha}([0, T] \times \overline{\Omega})$.

3 Blowup solutions

Throughout this section, we let Ω be a bounded domain in \mathbb{R}^n with a sufficiently regular boundary $\partial\Omega$. The unit outer normal vector to $\partial\Omega$ is denoted by ν , and let $\partial_\nu = \frac{\partial}{\partial \nu}$.

3.1 Resource-consumer type reaction

We consider the following system of equations

$$u_t = -au + u^p f(v), \quad \text{for } x \in \overline{\Omega}, \quad t > 0, \quad (3.1)$$

$$v_t = D\Delta v - bv - u^p f(v) + \kappa \quad \text{for } x \in \Omega, \quad t > 0, \quad (3.2)$$

where $D > 0$, $p > 1$, $a, b \in (0, \infty)$ and $\kappa \in [0, \infty)$. In equations (3.1)–(3.2), an arbitrary function $f = f(v)$ satisfies

$$f \in C^1([0, \infty)), \quad f(v) > 0 \quad \text{for } v > 0, \quad \text{and} \quad f(0) = 0. \quad (3.3)$$

We supplement system (3.1)–(3.2) with the homogeneous Neumann boundary condition for v :

$$\partial_\nu v = 0 \quad \text{for } x \in \partial\Omega, \quad t > 0, \quad (3.4)$$

and with bounded, nonnegative, and continuous initial data

$$u(x, 0) = u_0(x), \quad v(x, 0) = v_0(x) \quad \text{for } x \in \Omega. \quad (3.5)$$

When u has a diffusion term on the right-hand side of (3.1), the model (3.1)–(3.5) can be found in literature in context of several applications. Let us mention a few of them. For $p = 2$, $f(v) = v$, and suitably chosen coefficients, we obtain either the, so-called, *Brussellator* appearing in the modeling of chemical morphogenetic processes, the *Gray-Scott model* (also known as a *model of glycolysis*, or the *Schnackenberg model*.

Nonnegative solutions to the following initial value problem for the system of ordinary differential equations:

$$\frac{d}{dt}\bar{u} = -a\bar{u} + \bar{u}^p f(\bar{v}), \quad \frac{d}{dt}\bar{v} = -b\bar{v} - \bar{u}^p f(\bar{v}) + \kappa, \quad (3.6)$$

$$\bar{u}(0) = \bar{u}_0 \geq 0, \quad \bar{v}(0) = \bar{v}_0 \geq 0. \quad (3.7)$$

are global-in-time and bounded on $[0, \infty)$.

A behavior of solutions the system of ODEs from (3.6) depends essentially on its parameters. Let $p = 2$ and $f(v) = v$. For $a > 0$ and $b > 0$, this particular system has the trivial stationary nonnegative solution $(\bar{u}, \bar{v}) = (0, \kappa/b)$ which is an asymptotically stable solution. If, moreover, $\kappa^2 > 4a^2b$, we have two other nontrivial nonnegative stationary solutions which satisfy the following system of equations

$$\bar{u} = \frac{a}{\bar{v}} \quad \text{and} \quad -b\bar{v} - \frac{a^2}{\bar{v}} + \kappa = 0.$$

Every such a constant nontrivial and *stable* solution of ODEs is an *unstable* solution of the reaction-diffusion-ODE problem (3.1)-(3.5), which means that it has the diffusion-driven instability due to the autocatalysis $f_u(\bar{u}, \bar{v}) = -a + 2\bar{u}\bar{v} = a > 0$.

We show that there are non-constant initial conditions such that the corresponding solution to the reaction-diffusion-ODE problem (3.1)-(3.5) blows up at one point and in a finite time.

Here, without loss of generality, we assume that $0 \in \Omega$, where $\Omega \subset \mathbb{R}^n$ is an arbitrary bounded domain with a smooth boundary, and we rescale system (3.1)-(3.2) in such a way that the diffusion coefficient in equation (3.2) is equal to one.

In the following theorem, we prove that if u_0 is concentrated around an arbitrary point $x_0 \in \Omega$ (we choose $x_0 = 0$, for simplicity) and if $v_0(x) = \bar{v}_0$ is a constant function, then the corresponding solution to problem (3.1)-(3.5) blows up in a finite time.

Theorem 3.1. *Assume that $f \in C^1([0, \infty))$ satisfies $\inf_{v \geq R} f(v) > 0$ for each $R > 0$. Let $p > 1$ and $a, b, \kappa \in (0, \infty)$ be arbitrary. There exist numbers $\alpha \in (0, 1)$, $\varepsilon > 0$, and $R_0 > 0$ (depending on parameters of problem (3.1)-(3.5) and determined in the proof) such that if initial conditions $u_0, v_0 \in C(\bar{\Omega})$ satisfy*

$$0 < u_0(x) < \left(u_0(0)^{1-p} + 2\varepsilon^{-(p-1)} |x|^\alpha \right)^{-\frac{1}{p-1}} \quad \text{for all } x \in \Omega \quad (3.8)$$

$$u_0(0) \geq \left(\frac{a}{(1 - e^{(1-p)a}) F_0} \right)^{\frac{1}{p-1}}, \quad \text{where } F_0 = \inf_{v \geq R_0} f(v), \quad (3.9)$$

$$v_0(x) \equiv \bar{v}_0 > R_0 > 0 \quad \text{for all } x \in \Omega, \quad (3.10)$$

then the corresponding solution to problem (3.1)-(3.5) blows up at certain time $T_{\max} \leq 1$. Moreover, the following uniform estimates are valid

$$0 < u(x, t) < \varepsilon |x|^{-\frac{\alpha}{p-1}} \quad \text{and} \quad v(x, t) \geq R_0 \quad \text{for all } (x, t) \in \Omega \times [0, T_{\max}). \quad (3.11)$$

Total mass $\int_{\Omega} (u(x, t) + v(x, t)) dx$ of each nonnegative solution to the reaction-diffusion problem (3.1)-(3.5) with $D \geq 0$ does not blow up, and stays uniformly

bounded in $t > 0$. Indeed, we obtain that

$$\begin{aligned} \frac{d}{dt} \int_{\Omega} (u(x, t) + v(x, t)) \, dx &= - \int_{\Omega} (au(x, t) + bv(x, t)) \, dx + \int_{\Omega} \kappa \, dx \\ &\leq -\min\{a, b\} \int_{\Omega} (u(x, t) + v(x, t)) \, dx + \kappa|\Omega|. \end{aligned}$$

Theorem 3.1 shows that this *a priori* estimate is not sufficient to prevent the blow-up of solutions in a finite time.

3.1.1 Idea for proof of Theorem 3.1

We would like to give a sketch of the proof of Theorem 3.1. There are more details in [7].

It is an important key to solve the equation (3.1) with respect to $u(x, t)$, which leads to the following formula for all $(x, t) \in \Omega \times [0, T_{max}]$:

$$u(x, t) = \frac{e^{-at}}{\left(\frac{1}{u_0(x)^{p-1}} - (p-1) \int_0^t f(v(x, s)) e^{(1-p)as} \, ds \right)^{\frac{1}{p-1}}}. \quad (3.12)$$

Thus, it is clear that if we have an uniform lower bound for $v(x, t)$ and the initial condition satisfies (3.9), then the equation (3.12) leads to the following lower bound

$$u(x, t) \geq \frac{e^{-at}}{\left(\frac{1}{u_0(x)^{p-1}} - (1 - e^{(1-p)at}) a^{-1} F_0 \right)^{\frac{1}{p-1}}}. \quad (3.13)$$

This implies that $u(0, t)$ blows up in finite time because the right-hand side of inequality (3.13) for $x = 0$ blows up at some $t \leq 1$ under the assumption (3.9).

Therefore, it is sufficient to show the existence of a lower bound for v for all $(x, t) \in \Omega \times [0, T_{max}]$ in order to finish the proof of Theorem 3.1. We have the following lemma.

Lemma 3.2. *Assume that $v(x, t)$ is a solution of the reaction-diffusion equation (3.2) with an arbitrary function $u(x, t)$ and with a constant initial condition satisfying $v_0(x) \equiv \bar{v}_0 > 0$. Suppose that there are numbers $\varepsilon > 0$ and*

$$\alpha \in \left(0, \frac{2(p-1)}{p}\right) \quad \text{if } n \geq 2 \quad \text{and} \quad \alpha \in \left(0, \frac{p-1}{p}\right) \quad \text{if } n = 1 \quad (3.14)$$

such that

$$0 < u(x, t) < \varepsilon |x|^{-\frac{\alpha}{p-1}} \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}]. \quad (3.15)$$

Then, there is an explicit number $C_0 > 0$ independent of ε such that for all $\varepsilon > 0$ we have

$$v(x, t) \geq \min \left\{ \bar{v}_0, \frac{\kappa}{b} \right\} - \varepsilon^p C_0 \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}]. \quad (3.16)$$

Proof of Lemma 3.2. Let $z(t)$ be a solution of the problem

$$z_t = \Delta z - bz + \kappa, \quad z(x, 0) = \bar{v}_0 \quad (3.17)$$

with the homogeneous Neumann boundary conditions. Then, we can rewrite equation (3.2) in the integral form

$$v(t) = z(t) - \int_0^t e^{(t-s)(\Delta - bI)} (u^p f(v))(s) ds. \quad (3.18)$$

Here, we have a lower bound for $z(t)$:

$$z(t) = e^{-bt} \bar{v}_0 + \frac{\kappa}{b} (1 - e^{-bt}) \geq \min \left\{ \bar{v}_0, \frac{\kappa}{b} \right\} \quad \text{for all } t \in [0, T_{max}]. \quad (3.19)$$

Moreover, it is easy to see that there exists an upper bound for $v(x, t)$:

$$0 \leq v(x, t) \leq \max \left\{ \|v_0\|_\infty, \frac{\kappa}{b} \right\} \equiv R_1 \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}]. \quad (3.20)$$

Therefore, we compute the L^∞ -norm of equation (3.18) using (3.19) and (3.20), as well as the *a priori* assumption on u in (3.15) to obtain that

$$\begin{aligned} v(x, t) &\geq z(t) - \int_0^t \|e^{(t-s)(\Delta - b)} (u^p f(v))(s)\|_\infty ds \\ &\geq \min \left\{ \bar{v}_0, \frac{\kappa}{b} \right\} - \varepsilon^p C_q \left(\sup_{0 \leq v \leq R_1} f(v) \right) \int_0^t \left(1 + (t-s)^{-\frac{n}{2q}} \right) \| |x|^{-\frac{\alpha p}{p-1}} \|_q ds. \end{aligned} \quad (3.21)$$

Here, we have used the following well-known estimate

$$\|e^{t(\Delta - bI)} w_0\|_\infty \leq C_q \left(1 + t^{-\frac{n}{2q}} \right) \|w_0\|_q \quad \text{for all } t > 0, \quad (3.22)$$

which is satisfied for each $w_0 \in L^q(\Omega)$, each $q \in [1, \infty]$, and with a constant $C_q = C(q, n, \Omega)$ independent of w_0 and of t .

Hence, choosing $n/2 < q < n(p-1)/(\alpha p)$ to have $n/(2q) < 1$ and $|x|^{-\frac{\alpha p}{p-1}} \in L^q(\Omega)$, we finish the proof of this lemma. \square

By Lemma 3.2, the proof of Theorem 3.1 can be finished by showing an estimate (3.15). To do so, we need the following result on the Hölder continuity of $v(x, t)$.

Lemma 3.3. *Let $v(x, t)$ be a nonnegative solution of the problem*

$$v_t = \Delta v - bv - u^p f(v) + \kappa \quad \text{for } x \in \Omega, \quad t \in [0, T_{max}] \quad (3.23)$$

$$\frac{\partial v}{\partial n} = 0 \quad \text{on } \partial\Omega \times [0, T_{max}], \quad (3.24)$$

$$v(x, 0) = \bar{v}_0 \quad \text{for } x \in \Omega, \quad t \in [0, T_{max}], \quad (3.25)$$

where \bar{v}_0 is a positive constant and $u(x, t)$ is a nonnegative function. There exists a constant $\alpha \in (0, 1)$ satisfying also (3.14), such that if the a priori estimate (3.15) for $u(x, t)$ holds true with some $\varepsilon > 0$, then

$$|v(x, t) - v(y, t)| \leq \varepsilon^p C |x - y|^\alpha \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}),$$

where the constant $C > 0$ is independent of ε .

This lemma follows from a classical result on the Hölder continuity of solutions to the inhomogeneous heat equation.

Proof of Theorem 3.1. By assumption (3.8), we have $0 < u_0(x) < \varepsilon |x|^{-\frac{\alpha}{p-1}}$ for all $x \in \Omega$. Suppose that there exists $T_1 \in (0, 1)$ such that the solution of problem (3.1)-(3.5) exists on the interval $[0, T_1]$ and satisfies

$$\sup_{x \in \Omega} |x|^{\frac{\alpha}{p-1}} u(x, t) < \varepsilon \quad \text{for all } t < T_1, \quad \sup_{x \in \Omega} |x|^{\frac{\alpha}{p-1}} u(x, T_1) = \varepsilon. \quad (3.26)$$

First, we estimate the denominator of the fraction in (3.12) using assumption (3.8) as follows

$$\begin{aligned} & \frac{1}{u_0(x)^{p-1}} - (p-1) \int_0^t f(v(x, s)) e^{(1-p)as} ds \\ & \geq 2\varepsilon^{1-p} |x|^\alpha + \frac{1}{u_0(0)^{p-1}} - (p-1) \int_0^t f(v(0, s)) e^{(1-p)as} ds \\ & \quad + (p-1) \int_0^t (f(v(0, s)) - f(v(x, s))) e^{(1-p)as} ds. \end{aligned} \quad (3.27)$$

By the definition of T_{max} and formula (3.12), we immediately obtain

$$\frac{1}{u_0(0)^{p-1}} - (p-1) \int_0^t f(v(0, s)) e^{(1-p)as} ds > 0 \quad \text{for all } t \in [0, T_{max}). \quad (3.28)$$

Next, we use our hypothesis (3.26) together with the Hölder continuity of $v(x, t)$ established in Lemma 3.3 to find constants $C > 0$ and $\alpha \in (0, 1)$, the both independent of $\varepsilon \geq 0$, such that

$$(p-1) \int_0^t |f(v(0, s)) - f(v(x, s))| e^{(1-p)as} ds \leq \varepsilon^p C a^{-1} |x|^\alpha \quad (3.29)$$

for all $(x, t) \in \Omega \times [0, T_1]$. Consequently, we obtain the lower bound for the denominator in (3.12)

$$\frac{1}{u_0(x)^{p-1}} - (p-1) \int_0^t f(v(x, s)) e^{(1-p)as} ds \geq (2\varepsilon^{-(p-1)} - \varepsilon^p C a^{-1}) |x|^\alpha \quad (3.30)$$

for all $(x, t) \in \Omega \times [0, T_1]$. Finally, we choose $\varepsilon > 0$ so small that $2\varepsilon^{-(p-1)} - \varepsilon^p C a^{-1} > \varepsilon^{-(p-1)}$ and we substitute estimate (3.30) in equation (3.12) to obtain

$$0 < u(x, t) \leq \frac{e^{-at}}{\left((2\varepsilon^{-(p-1)} - \varepsilon^p C a^{-1})|x|^\alpha\right)^{\frac{1}{p-1}}} < \frac{\varepsilon}{|x|^{\frac{\alpha}{p-1}}} \quad \text{for all } (x, t) \in \Omega \times [0, T_1].$$

This inequality for $t = T_1$ contradicts our hypothesis (3.26). \square

3.2 Activator-inhibitor type reaction

We consider the following initial-boundary value problem for a reaction-diffusion-ODE system:

$$u_t = -au + \frac{u^p}{v^q}, \quad \text{for } x \in \overline{\Omega}, \quad t > 0, \quad (3.31)$$

$$v_t = D\Delta v - bv + \gamma \frac{u^r}{v^s} \quad \text{for } x \in \Omega, \quad t > 0, \quad (3.32)$$

supplemented with the the initial data $u_0, v_0 \in C(\overline{\Omega})$ such that

$$u(x, 0) = u_0(x) > 0, \quad v(x, 0) = v_0(x) > 0 \quad \text{for all } x \in \overline{\Omega} \quad (3.33)$$

and with the Neumann boundary conditions for v ;

$$\partial_\nu v = 0 \quad \text{for } x \in \partial\Omega, \quad t > 0. \quad (3.34)$$

Here, $D > 0$, a, b, γ are nonnegative constants, and the nonlinearity exponents in (3.31)-(3.32) satisfy

$$p > 1, \quad q > 0, \quad r > 0, \quad s \geq 0. \quad (3.35)$$

From the initial conditions, we have $\inf u_0 \equiv \inf_{x \in \Omega} u_0(x) > 0$ and $\inf v_0 \equiv \inf_{x \in \Omega} v_0(x) > 0$.

In the following, for simplicity of notation, we use the quantities

$$f_{0,T} \equiv \inf_{t \in [0,T]} e^{a(1-p+q)t} \quad \text{and} \quad g_{1,T} \equiv \sup_{t \in [0,T]} e^{b(1-r+s)t}. \quad (3.36)$$

For $p > 1$, it is easy to see that the reaction-diffusion-ODE system (3.31)-(3.32) has the diffusion-driven instability at a constant steady state. When the right-hand side of the equation (3.31) has a diffusion term and the exponents satisfy

$$0 < \frac{p-1}{r} < \frac{q}{s+1}, \quad (3.37)$$

the system (3.31)-(3.32) is an activator-inhibitor system proposed by Gierer and Meinhardt. It has been widely used to model various biological pattern formations.

First, we consider the the *kinetic system* of ordinary differential equations associated with (3.31)–(3.32):

$$\frac{d}{dt}\bar{u} = -a\bar{u} + \frac{\bar{u}^p}{\bar{v}^q}, \quad \frac{d}{dt}\bar{v} = -b\bar{v} + \gamma \frac{\bar{u}^r}{\bar{v}^s}. \quad (3.38)$$

When $a = b = \gamma = 1$, it turns out that this dynamics already exhibits various kinds of interesting behaviors including the convergence to the equilibria $(0, 0)$ and $(1, 1)$, periodic solutions, unbounded oscillating global solutions, and a blowup of solutions in finite time [11]. In particular, if inequalities (3.37) and $p - 1 \leq r$ are satisfied, then solutions of (3.38) are global-in-time, while there are solutions blowing up in finite time under the conditions (3.37) and $p - 1 > r$. Thus, our Theorem 3.4 shows that the diffusion of the inhibitor described by $v(x, t)$ induces a *blowup* of the space-inhomogeneous and non-diffusing activator $u(x, t)$ – also in the case when space-homogeneous solutions are global-in-time.

In the following, without loss of generality, we assume that $0 \in \Omega$. Moreover, system (3.31)–(3.32) is rescaled in such a way so that the diffusion coefficient in equation (3.32) is equal to one.

We prove that if u_0 is sufficiently well concentrated around an arbitrary point $x_0 \in \Omega$ (here, for simplicity of notation, we choose $x_0 = 0$), if v_0 is a constant function, and if $\gamma > 0$ is sufficiently small then the corresponding solution to problem (3.31)–(3.34) blows up in a finite time $T_{max} > 0$, *without additional restrictions* on the exponents in nonlinearities.

Theorem 3.4. *Assume the nonlinearity exponents satisfy (3.35) and let $T > 0$ be arbitrary. Suppose that $0 \in \Omega$ and*

- *there exists a number*

$$\alpha \in \left(0, \frac{2(p-1)}{r}\right) \quad \text{if } n \geq 2 \quad \text{and} \quad \alpha \in \left(0, \frac{p-1}{r}\right) \quad \text{if } n = 1$$

such that $u_0 \in C(\bar{\Omega})$ satisfies

$$0 < u_0(x) \leq \frac{1}{(u_0(0)^{1-p} + 2|x|^\alpha)^{\frac{1}{p-1}}} \quad \text{for all } x \in \Omega, \quad (3.39)$$

- *$v(x, 0) = \bar{v}_0$ is a constant such that*

$$0 < \bar{v}_0 < R_0 \equiv \left(T(p-1)f_{0,T}(\inf_{x \in \Omega} u_0(x))^{p-1}\right)^{\frac{1}{q}} \quad \text{for all } x \in \Omega, \quad (3.40)$$

- *$\gamma \in [0, \gamma_0)$, where $\gamma_0 = \gamma_0(u_0, \bar{v}_0, T, p, q, r, s, n)$ is a certain number determined in the proof.*

Then the corresponding solution to problem (3.31)–(3.34) blows up at some $T_{max} \leq T$. Moreover, the following uniform estimates are valid

$$0 < u(x, t) < |x|^{-\frac{\alpha}{p-1}} \quad \text{and} \quad 0 < v(x, t) < R_0 \quad (3.41)$$

for all $(x, t) \in \Omega \times [0, T_{max})$.

3.2.1 Idea for proof of Theorem 3.4

To show that some solutions to problems (3.31)-(3.34) blow up in a finite time, we first notice that if $(u(x, t), v(x, t))$ is their solution, then the functions $u(x, t)e^{at}$ and $v(x, t)e^{bt}$ satisfy the following boundary-value problem

$$u_t = \frac{u^p}{v^q} f(t) \quad \text{for } x \in \bar{\Omega}, \quad t > 0, \quad (3.42)$$

$$v_t = D\Delta v + \gamma \frac{u^r}{v^s} g(t) \quad \text{for } x \in \Omega, \quad t > 0, \quad (3.43)$$

$$\partial_\nu v = 0 \quad \text{for } x \in \partial\Omega, \quad t > 0, \quad (3.44)$$

$$u(x, 0) = u_0(x), \quad v(x, 0) = v_0(x), \quad (3.45)$$

where

$$f(t) = e^{a(1-p+q)t} \quad \text{and} \quad g(t) = e^{b(1-r+s)t}. \quad (3.46)$$

Obviously, it suffices to prove a blowup of solutions to the new problem (3.42)-(3.45).

In the following, we would like to give a sketch of the proof of Theorem 3.4. There are more details in [2].

First, we note that, for every nonnegative $u_0, v_0 \in C(\bar{\Omega})$, $u(x, t)$ and $v(x, t)$ satisfy

$$u(x, t) \geq \inf u_0 \quad \text{and} \quad v(x, t) \geq \inf v_0 \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}). \quad (3.47)$$

Now, for a given function $v(x, t)$, we solve equation (3.31) with respect to $u(x, t)$ to obtain the explicit formula for $u(x, t)$:

$$u(x, t) = \frac{1}{\left(\frac{1}{u_0(x)^{p-1}} - (p-1) \int_0^t \frac{f(\tau)}{v(x, \tau)^q} d\tau \right)^{\frac{1}{p-1}}}. \quad (3.48)$$

From the assumption (3.39) for $u_0(x)$, we can obtain the blowup of $u(x, t)$ at $x = 0$ in finite time if $v(x, t)$ is uniformly bounded from above. Next lemma shows that an upper bound for $v(x, t)$ leads to the blowup of $u(x, t)$ in a finite time indeed.

Lemma 3.5. *Let $(u(x, t), v(x, t))$ be a nonnegative solution to (3.42)-(3.45) with $\varepsilon \geq 0$ and $D > 0$. Suppose that for some constant $T > 0$ we have*

$$0 < v(x, t) < R_0 = \left(T(p-1)f_{0,T}(\inf u_0)^{p-1} \right)^{\frac{1}{q}} \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}). \quad (3.49)$$

Then $u(x, t)$ blows up at certain $T_{max} \leq T$.

Proof of Lemma 3.5. Applying the comparison principle to equation (3.42), we obtain the estimate

$$u(x, t) \geq \bar{u}_1(t) \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}), \quad (3.50)$$

where $\bar{u}_1 = \bar{u}_1(t)$ is the solution of the Cauchy problem

$$\frac{d}{dt} \bar{u}_1 = \frac{\bar{u}_1^p}{R_0^q} f_{0,T}, \quad \bar{u}(0) = \inf u_0. \quad (3.51)$$

The function \bar{u}_1 may be computed explicitly:

$$\bar{u}_1(t) = \frac{1}{((\inf u_0)^{1-p} - t(p-1)R_0^{-q}f_{0,T})^{\frac{1}{p-1}}}. \quad (3.52)$$

Recalling the definition of the number R_0 in (3.49), we obtain that $\bar{u}_1(t)$ blows up at $t = T$, which due to inequality (3.50) implies that $T_{max} \leq T$. \square

From Lemma 3.5, it is sufficient to obtain an upper bound for $v(x, t)$ to finish the proof of Theorem 3.4. The following lemma shows that a priori estimate for $u(x, t)$ similar to (3.15) is important to lead to the upper bound for $v(x, t)$.

Lemma 3.6. *Let $u(x, t)$ and $v(x, t)$ be a solution to problem (3.31)-(3.33). Suppose that there is a number*

$$\alpha \in \left(0, \frac{2(p-1)}{r}\right) \quad \text{if } n \geq 2 \quad \text{and} \quad \alpha \in \left(0, \frac{p-1}{r}\right) \quad \text{if } n = 1 \quad (3.53)$$

such that, a priori, the following inequality holds true

$$0 < u(x, t) < |x|^{-\frac{\alpha}{p-1}} \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}). \quad (3.54)$$

Then, there is an explicit number $C_0 > 0$ such that for all $\gamma \geq 0$ we have

$$\|v(t)\|_\infty \leq \|v_0\|_\infty + \gamma C_0 \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}). \quad (3.55)$$

Proof of Lemma 3.6. We use the following integral formulation of equation (3.32)

$$v(t) = e^{t\Delta} v_0 + \gamma \int_0^t e^{(t-\tau)\Delta} \left(\frac{u^r(\tau)}{v^s(\tau)} g(\tau) \right) d\tau. \quad (3.56)$$

Here, we recall the following well-known estimates for the heat semigroup which are valid for all $t > 0$, $D > 0$, and all $w_0 \in L^\infty(\Omega)$:

$$\|e^{tD\Delta} w_0\|_\infty \leq \|w_0\|_\infty \quad \text{and} \quad \|e^{tD\Delta} w_0\|_\infty \leq C_\ell (1 + t^{-\frac{n}{2\ell}}) \|w_0\|_\ell \quad (3.57)$$

for each $\ell \in [1, \infty]$, with a constant $C_\ell = C(\ell, n, D, \Omega)$ independent of w_0 and of t .

Now, we compute the L^∞ -norm of equation (3.56). Using inequalities (3.57), the lower bound of v in (3.47) as well as the *a priori* assumption on u in (3.54) we obtain the estimate

$$\begin{aligned} \|v(t)\|_\infty &\leq \|v_0\|_\infty + \gamma \int_0^t \left\| e^{(t-\tau)\Delta} \left(\frac{u^r(\tau)}{v^s(\tau)} g(\tau) \right) \right\|_\infty d\tau \\ &\leq \|v_0\|_\infty + \gamma C_\ell (\inf v_0)^{-s} g_{1,T} \int_0^t (1 + (t-\tau)^{-\frac{n}{2\ell}}) \left\| |x|^{-\frac{\alpha r}{p-1}} \right\|_\ell d\tau, \end{aligned} \quad (3.58)$$

where the constant $g_{1,T}$ is defined in (3.36). Here, we choose $n/2 < \ell < n(p-1)/(\alpha r)$ to have $n/(2\ell) < 1$ and $|x|^{-\frac{\alpha r}{p-1}} \in L^\ell(\Omega)$ to finish the proof of lemma. \square

We can show the Hölder continuity of v , which is similar to Lemma 3.3. Indeed, there exists a constant $\alpha \in (0, 1)$ satisfying also (3.53) and a number $C > 0$, the both independent of $\gamma > 0$, such that

$$|v(x, t) - v(y, t)| \leq \gamma C |x - y|^\alpha \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}).$$

We are ready to prove a result on the one-point blowup of solutions to the reaction-diffusion-ODE problem (3.31)-(3.34).

Proof of Theorem 3.4. Let $(u(x, t), v(x, t))$ be a solution to the problem (3.42)-(3.45). By Lemmas 3.5 and 3.6, it suffices to show the following estimate

$$0 < u(x, t) < |x|^{-\frac{\alpha}{p-1}} \quad \text{for all } (x, t) \in \Omega \times [0, T_{max}), \quad (3.59)$$

under the assumption that $\gamma > 0$ is sufficiently small. Let $T > 0$ be a number such that inequality (3.40) holds true.

By assumption (3.39), we have $0 < u_0(x) < |x|^{-\frac{\alpha}{p-1}}$ for all $x \in \Omega$, hence, by a continuity argument, inequality (3.59) is satisfied on a certain initial time interval. Suppose that there exists $T_1 \in (0, \min\{T_{max}, T\})$ such that the solution of problem (3.42)-(3.45) exists on the interval $[0, T_1]$ and satisfies

$$\sup_{x \in \Omega} |x|^{\frac{\alpha}{p-1}} u(x, t) < 1 \quad \text{for all } t < T_1, \quad \sup_{x \in \Omega} |x|^{\frac{\alpha}{p-1}} u(x, T_1) = 1. \quad (3.60)$$

We are going to use the explicit formula (3.48) for $u(x, t)$ and the Hölder continuity of $v(x, t)$ to obtain a contradiction with equality (3.60).

First, notice that assumption (3.39) can be written as $u_0(x)^{1-p} \geq 2|x|^\alpha + u_0(0)^{1-p}$. Thus, we may estimate the denominator of the fraction in (3.48) using this assumption as follows

$$\begin{aligned} &\frac{1}{u_0(x)^{p-1}} - (p-1) \int_0^t \frac{f(\tau)}{v(x, \tau)^q} d\tau \\ &\geq 2|x|^\alpha + \frac{1}{u_0(0)^{p-1}} - (p-1) \int_0^t \frac{f(\tau)}{v(0, \tau)^q} d\tau \\ &\quad + (p-1) \int_0^t \left(\frac{1}{v(0, \tau)^q} - \frac{1}{v(x, \tau)^q} \right) f(\tau) d\tau. \end{aligned} \quad (3.61)$$

By the definition of T_{max} and due to formula (3.48), we immediately obtain

$$\frac{1}{u_0(0)^{p-1}} - (p-1) \int_0^t \frac{f(\tau)}{v(0, \tau)^q} d\tau > 0 \quad \text{for all } t \in [0, T_{max}). \quad (3.62)$$

Next, we use our hypotheses (3.60) implying estimate (3.55) and the Hölder continuity of $v(x, t)$ as well as the lower bound of $v(x, t)$ in (3.47), to find constants $C > 0$ and $\alpha \in (0, 1)$, satisfying also (3.53), such that the following inequality is satisfied:

$$(p-1) \int_0^t \left| \frac{1}{v(0, \tau)^q} - \frac{1}{v(x, \tau)^q} \right| f(\tau) d\tau \leq \gamma C(T) |x|^\alpha \quad (3.63)$$

for all $(x, t) \in \Omega \times [0, T_1]$. Consequently, applying inequalities (3.62) and (3.63) in (3.61) we obtain the following lower bound for the denominator in (3.48)

$$\frac{1}{u_0(x)^{p-1}} - (p-1) \int_0^t \frac{f(\tau)}{v(x, \tau)^q} d\tau \geq (2 - \gamma C) |x|^\alpha \quad (3.64)$$

for all $(x, t) \in \Omega \times [0, T_1]$. Finally, we choose $\gamma > 0$ so small that $\gamma C < 1$ (hence $2 - \gamma C > 1$) and we substitute estimate (3.64) into equation (3.52) to obtain

$$0 < u(x, t) \leq \frac{1}{\left((2 - \gamma C) |x|^\alpha \right)^{\frac{1}{p-1}}} < \frac{1}{|x|^{\frac{\alpha}{p-1}}} \quad \text{for all } (x, t) \in \Omega \times [0, T_1].$$

This inequality for $t = T_1$ contradicts our hypothesis (3.60). □

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